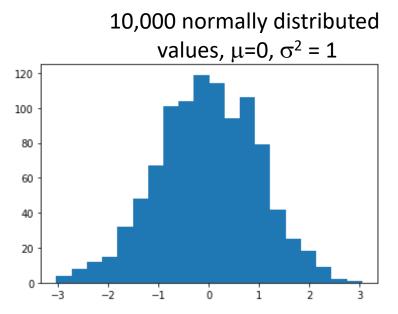
Math Methods and Experimental Physics

Monte Carlo Methods or why I showed the unif. dist. Central limit theorem or why I showed the normal dist. Multi-dimensional pdfs Correlation Error propagation

Monte Carlo sampling

Problem: We have a pdf: f(x) defined over $(-\infty, \infty)$. We want to produce a list of random numbers that are sampled from f(x). In numpy, you can find a long list of common pdfs, to sample from. But let's say f(x) is not on this list.



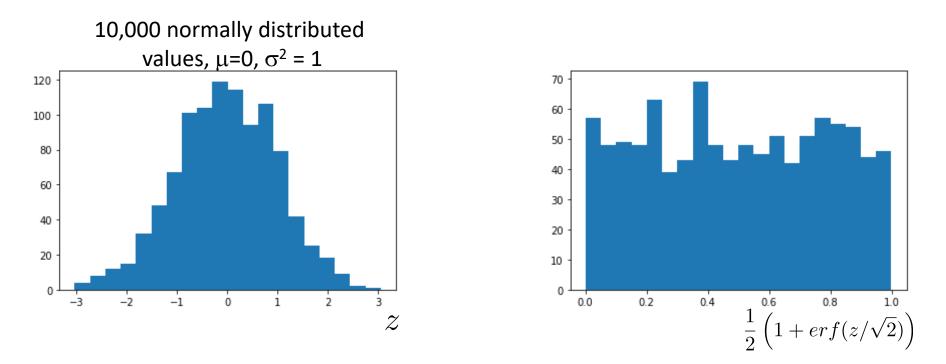
A histogram of 1000 random numbers that follow a normal distribution (μ =0, σ =1) using numpy.random.normal()

The most basic thing you'll find is a pseudo-random number generator of the uniform distribution.

Monte Carlo sampling: Inverse transform

Let F(x) be the cumulative distribution function (cdf) of f(x).

If a random variable z is distributed according to f(x), then F(z) (= F(f(x))) will be uniformly distributed in [0,1].



Monte Carlo sampling: Inverse transform

Let's invert this process!

- a) Generate a uniformly distributed list y in [0,1].
- **b)** Find $x = F^{-1}(y)$

Then x, will be distributed following f(x)

Central limit theorem

In the limit of n large, the sum of n independent continuous random variables x_i with means μ_i and variances σ^2_i becomes a Gaussian random variable with mean

$$\mu = \sum_i \mu_i$$

and with variance

$$\sigma^2 = \sum_i \sigma_i^2$$

The importance of this theorem is that the form of $pdf(x_i)$ is irrelevant.

Central limit theorem – simple example

You have N measurements of a voltage, V_i. The voltage variances, are δV_i^2

The average voltage <V> is normally distributed with mean:

$$\bar{V} = \frac{1}{N} \sum_{i} V_i$$

And variance (unbiased):

$$\delta \bar{V}^2 = \frac{1}{N-1} \sum_i \delta V_i^2$$

And you don't care whether V_i are normally distributed or not. (*) I distinguish <V> a distribution and \overline{V} , a point estimate.

Multi-dimensional pdfs

A single observation can result in multiple values.

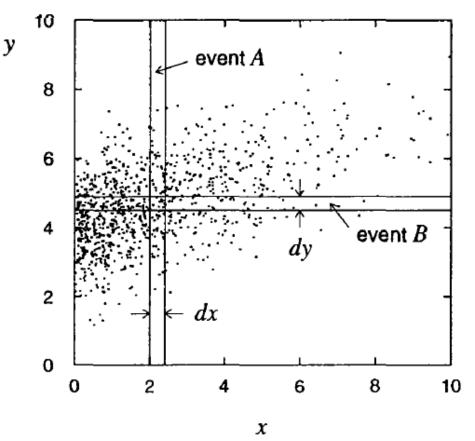
Example: A neutrino detected in IceCube results in measurement of direction in the sky (δ ,RA), energy, time, etc.

Multi-dimensional distributions

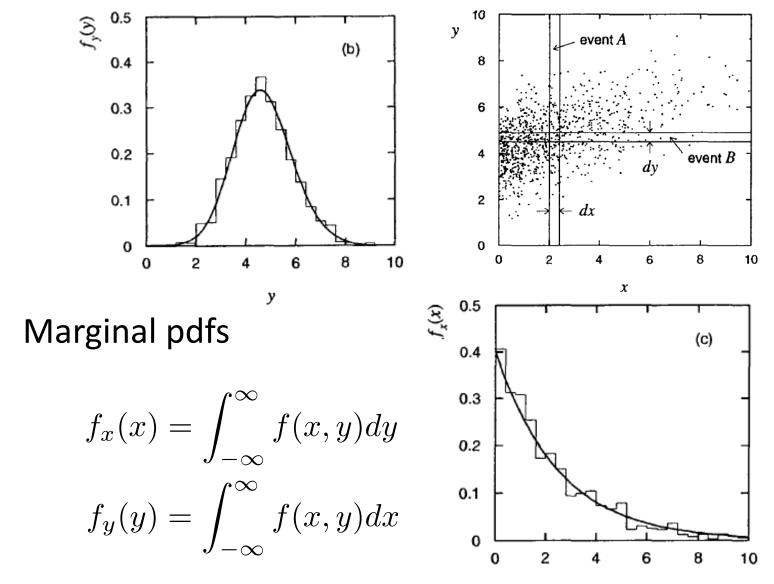
We can have a joint pdf f(x,y) such that:

$$\int_{S} f(x, y) dx dy = 1$$

f(x,y)dxdy is the probability in the squared defined by (x,y) and (x+dx,y+dy) This is the book example Histograms are useful too.



Multi-dimensional distributions

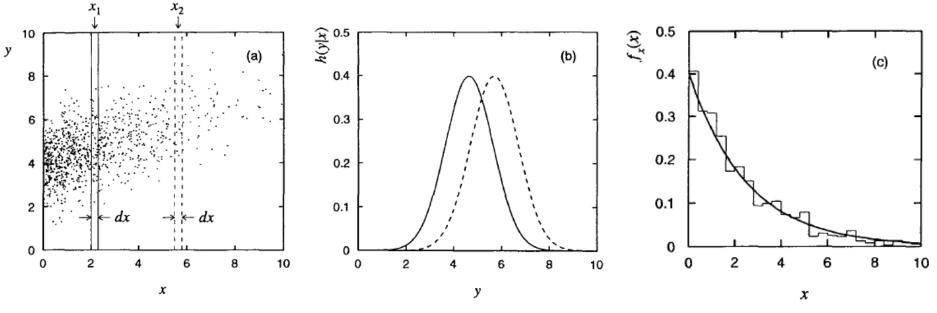


Independence of multi-dimensional data

We can define conditional pdf:

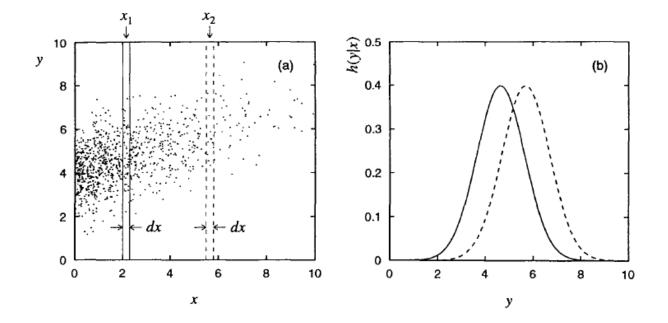
$$h(y|x) = \frac{f(x,y)}{f_x(x)} = \frac{f(x,y)}{\int f(x,y')dy'} \qquad g(x|y) = \frac{f(x,y)}{f_y(y)} = \frac{f(x,y)}{\int f(x',y)dx'}$$

Note that h(y|x) is a function of y given the *parameter* x.



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Independent multi-dimensional data



If x,y are independent, then h(y|x) and g(x|y) are independent of the parameter x and y respectively. In the plot above, x and y are not independent.

<u>Covariance</u>

$$V_{xy} = E((x - \bar{x})(y - \bar{y})) = E(xy) - \bar{x}\bar{y} = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} xyf(x, y)dxdy - \bar{x}\bar{y}$$

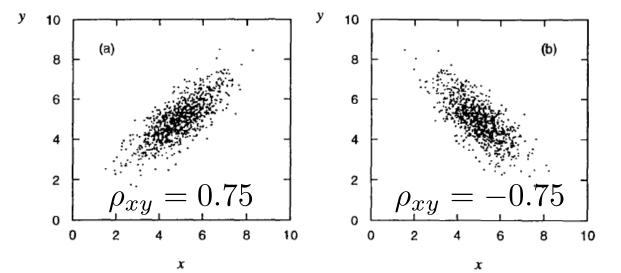
We can define also V_{xx} , V_{yy} , V_{yx} to form a 2x2 symmetric matrix. This can easily be extended to more dimensions. Since this matrix is symmetric it can always be diagonalized. The eigenvectors define new <u>decorrelated variables</u> x', y' (Whether the decorrelated variables have physical meaning, it's another issue).

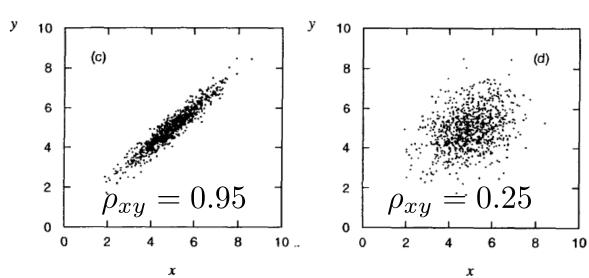
Defining:
$$\rho_{xy} = \frac{V_{xy}}{\sigma_x \sigma_y}$$

The (unitless) correlation coefficient matrix is:

$$Corr(x,y) = \left(\begin{array}{c} 1, \rho_{xy} \\ \rho_{xy}, 1 \end{array}\right)$$

Covariance



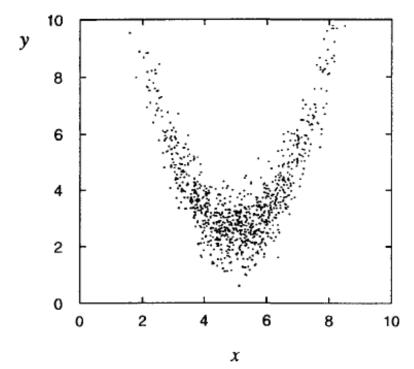


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Covariance

Uncorrelated data (x and y) have $\rho_{xy} = 0$

But, it's possible to have $\rho_{xy} = 0$ even when there is a correlation. (You can do more things to data, than a linear transformation)



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Error propagation

So:

Let's have a measurement of \vec{x} . The joint pdf $f(\vec{x})$ is unknown, but the expectation values $\vec{\mu}$ and co-variance matrix V_{ii} are known (Given the data you can always get point estimates).

Let's have $y(\vec{x})$ be a function of our measurements. What is σ_{v} ?

$$y(\vec{x}) \sim y(\vec{\mu}) + \sum_{i} \left. \frac{\partial y}{\partial x_{i}} \right|_{\vec{\mu}} (x_{i} - \mu_{i})$$

Clearly: $E[y(\vec{x})] \sim y(\vec{\mu})$ $E[y^2(\vec{x})] = y^2(\vec{\mu}) + 2y(\vec{\mu}) \sum_{i} \frac{\partial y}{\partial x_i} |_{\mu} E[x_i - \mu_i]$ $+E\left|\left(\left(\sum_{i} \frac{\partial y}{\partial x_{i}}\right|_{\vec{\mu}} (x_{i} - \mu_{i})\right)\left(\sum_{i} \frac{\partial y}{\partial x_{j}}\right|_{\vec{\mu}} (x_{j} - \mu_{j})\right)\right|$

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Error propagation
So:
$$E[y^2] \sim y^2(\vec{\mu}) + \sum_{i,j} \frac{\partial y}{\partial x_i} \frac{\partial y}{\partial x_j} \Big|_{\vec{\mu}} V_{ij}$$

And we can the estimate of the variance of y:

$$\sigma_y^2 \sim E[y^2(\vec{x}] - (E[y(\vec{x}])^2) = \sum_{i,j} \left. \frac{\partial y}{\partial x_i} \frac{\partial y}{\partial x_j} \right|_{\vec{\mu}} V_{ij}$$

For the simple case: $y = x_1 + x_2$

$$\sigma_y^2 = \sigma_1^2 + \sigma_2^2 + 2\frac{\partial y}{\partial x_1}\frac{\partial y}{\partial x_2}V_{12}$$

And for uncorrelated x₁, x₂ ("Errors add in quadrature")

$$\sigma_y^2 = \sigma_1^2 + \sigma_2^2$$