

Rescaling in Perturbation Theory

16.1

Example: $\epsilon x^2 - 1 = 0$

Unperturbed equation: $1 = 0$ - no solutions

\Rightarrow Don't know the leading order of both solutions

$x = \delta y + \dots$: $x = \delta y \Rightarrow \epsilon \delta^2 y^2 - 1 = 0$

Dominant balance: $\epsilon \delta^2 = 1 \Rightarrow \delta = \frac{1}{\sqrt{\epsilon}} \Rightarrow y^2 - 1 = 0$

$\Rightarrow y = \pm 1 \Rightarrow x = \delta y = \pm \frac{1}{\sqrt{\epsilon}}$

Example: $\epsilon x^2 + x - 1 = 0$

Unperturbed equation: $x - 1 = 0 \Rightarrow$ one solution: $x = 1$

\Rightarrow Don't know the leading order behavior of one of the solutions

$x = \delta y + \dots$: $x = \delta y \Rightarrow \epsilon \delta^2 y^2 + \delta y - 1 = 0$

Dominant balance:

$\epsilon \delta^2 = \delta \Rightarrow \delta = \frac{1}{\epsilon} \Rightarrow \frac{1}{\epsilon} y^2 + \frac{1}{\epsilon} y - 1 = \frac{1}{\epsilon} (y^2 + y - \epsilon) = 0 \Rightarrow \begin{cases} y = 0 + \dots \\ y = -1 + \dots \end{cases}$

$\Rightarrow x = \delta y = -\frac{1}{\epsilon} + \dots$

Example: $-\epsilon x^2 + x^2 - 2x + 1 = 0$

Unperturbed equation: $x^2 + 2x + 1 = 0 \Rightarrow$ two solutions: $x_{1,2} = -1$

• Degeneracy \rightarrow expect nontrivial scaling of corrections to leading order. Since we don't know the behavior of subleading terms

$\Rightarrow x = 1 + \delta y + \dots$: $x = \delta y \rightarrow$

\uparrow
solution of unperturbed eq.

$-\epsilon(1 + 2\delta y + \delta^2 y^2) + (1 + 2\delta y + \delta^2 y^2) - 2(1 + \delta y) + 1 = (1 - \epsilon)\delta^2 y^2 - 2\epsilon \delta y - \epsilon = 0$

Dominant balance:

$\delta^2 = \epsilon \Rightarrow \delta = \sqrt{\epsilon} \Rightarrow \epsilon y^2 - 2\epsilon^{3/2} y - \epsilon = 0 \rightarrow y = \pm 1$

$\Rightarrow x = 1 + \delta y = 1 \pm \sqrt{\epsilon} + \dots$

Perturbation Theory for Degenerate Matrices

$$(A + \epsilon B)\vec{x} = \lambda \vec{x}$$

$$\left. \begin{aligned} \lambda_i &= \lambda_i^{(0)} + \epsilon \lambda_i^{(1)} + \dots \\ \vec{x}_i &= \vec{x}_i^{(0)} + \epsilon \vec{x}_i^{(1)} + \dots \end{aligned} \right\} (A + \epsilon B)(\vec{x}_i^{(0)} + \epsilon \vec{x}_i^{(1)} + \dots) = (\lambda_i^{(0)} + \epsilon \lambda_i^{(1)} + \dots)(\vec{x}_i^{(0)} + \epsilon \vec{x}_i^{(1)} + \dots)$$

Σ^0 : $A\vec{x}_i^{(0)} = \lambda_i^{(0)}\vec{x}_i^{(0)}$

$\Rightarrow \lambda_i^{(0)} = a_i$ - eigenvalue of A , $\vec{x}_i^{(0)}$ - some eigenvector, which corresponds to a_i

We have not determined $\vec{x}_i^{(0)}$, if $\lambda_i^{(0)}$ is degenerate.

If $\lambda_i^{(0)}$ is n -times degenerate, $\vec{x}_i^{(0)} = \alpha_1^i \vec{e}_1 + \alpha_2^i \vec{e}_2 + \dots + \alpha_n^i \vec{e}_n$

Coefficients α_i are not determined by 0th order equations, they are determined by higher order equations!

Σ^1 : $A\vec{x}_i^{(1)} + B\vec{x}_i^{(0)} = \lambda_i^{(0)}\vec{x}_i^{(1)} + \lambda_i^{(1)}\vec{x}_i^{(0)}$

Multiply by \vec{f}_j on the left: $a_j(\vec{f}_j \cdot \vec{x}_i^{(1)}) + (\vec{f}_j \cdot B\vec{x}_i^{(0)}) = a_i(\vec{f}_j \cdot \vec{x}_i^{(1)}) + \lambda_i^{(1)}\vec{x}_i^{(0)}$

- a) $j = 1, \dots, n \rightarrow n$ equations for eigenvalue correction $\lambda_i^{(1)}$
- b) $j \neq 1, \dots, n \Rightarrow N-n$ equations for eigenvector correction $\vec{x}_i^{(1)}$

a) $(\vec{f}_j \cdot B\vec{x}_i^{(0)}) = \sum_{k=1}^n \alpha_k^i \underbrace{(\vec{f}_j \cdot B\vec{e}_k)}_{\tilde{B}_{jk}} = \lambda_i^{(1)} \sum_{k=1}^n \alpha_k^i \underbrace{(\vec{f}_j \cdot \vec{e}_k)}_{\delta_{jk}} \Rightarrow \tilde{B}\vec{\alpha}^i = \lambda_i^{(1)}\vec{\alpha}^i$

If \tilde{B} is non-degenerate, this eigenproblem determines both $\lambda_i^{(1)}$ (1st order term in eigenvalue expansion) and $\vec{\alpha}^i = (\alpha_1^i, \dots, \alpha_n^i)$ (0th order term in eigenvector expansion)

If \tilde{B} is also degenerate, α_k^i might (or might not be) determined by higher orders of pert. theory

Example 1

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

$$\vec{f}_1 = \vec{e}_1 = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad \vec{f}_2 = \vec{e}_2 = \begin{pmatrix} 0 \\ 1 \end{pmatrix}, \quad \lambda_{1,2}^{(0)} = 1$$

$$\vec{x}_i^{(0)} = \alpha_1^i \vec{e}_1 + \alpha_2^i \vec{e}_2; \quad \tilde{B}_{jk} = \vec{f}_j \cdot B \vec{e}_k = \delta_{jk} = B \text{ -degenerate!}$$

$$\Rightarrow \lambda_i^{(1)} = 1, \quad \alpha_{1,2}^i \text{ -arbitrary} \rightarrow$$

$$(\text{Solve exactly: } \lambda_{1,2} = 1 + \varepsilon, \quad \vec{x}_i = \alpha_1^i \vec{e}_1 + \alpha_2^i \vec{e}_2, \quad \forall \alpha_{1,2}^i)$$

Example 2

$$A = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}, \quad B = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$\tilde{B}_{jk} = \vec{f}_j \cdot B \vec{e}_k = B_{jk} \Rightarrow \lambda_i^{(0)2} - 1 = 0 \Rightarrow \lambda_i^{(0)} = \pm 1 \text{ -non-degen.!}$$

$$\lambda_i^{(0)} = +1: \quad \vec{\alpha} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \Rightarrow \vec{x}_i^{(0)} = \vec{e}_1 + \vec{e}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\lambda_i^{(0)} = -1: \quad \vec{\alpha} = \begin{pmatrix} 1 \\ -1 \end{pmatrix} \Rightarrow \vec{x}_i^{(0)} = \vec{e}_1 - \vec{e}_2 = \begin{pmatrix} 1 \\ -1 \end{pmatrix}$$