Chapter 16

Transporting densities

In chapters 2, 3, 7 and 8 we learned how to track an individual trajectory, and saw that such a trajectory can be very complicated. In chapter 4 we studied a small neighborhood of a trajectory and learned that such neighborhood can grow exponentially with time, making the concept of tracking an individual trajectory for long times a purely mathematical idealization.

While the trajectory of an individual representative point may be highly convoluted, as we shall see, the density of these points might evolve in a manner that is relatively smooth. The evolution of the density of representative points is for this reason (and other that will emerge in due course) of great interest. So are the behaviors of other properties carried by the evolving swarm of representative points.

We shall now show that the global evolution of the density of representative points is conveniently formulated in terms of linear action of evolution operators. We shall also show that the important, long-time "natural" invariant densities are unspeakably unfriendly and essentially uncomputable everywhere singular functions with support on fractal sets. Hence, in chapter 17 we rethink what is it that the theory needs to predict ("expectation values" of "observables"), relate these to the eigenvalues of evolution operators, and in chapters 18 to 20 show how to compute these without ever having to compute a "natural" invariant density \( \rho_0 \).

16.1 Measures

Do I then measure, O my God, and know not what I measure?

—St. Augustine, The confessions of Saint Augustine

A fundamental concept in the description of dynamics of a chaotic system is that of measure, which we denote by \( d\mu(x) = \rho(x) dx \). An intuitive way to define and construct a physically meaningful measure is by a process of coarse-graining.

Consider a sequence 1, 2, ..., \( n \), ... of increasingly refined partitions of state space, figure 16.1, into regions \( M_i \) defined by the characteristic function

\[
\chi_i(x) = \begin{cases} 
1 & \text{if } x \in M_i, \\
0 & \text{otherwise}. 
\end{cases}
\]

(16.1)

A coarse-grained measure is obtained by assigning the "mass," or the fraction of trajectories contained in the \( i \)th region \( M_i \subset M \) at the \( n \)th level of partitioning of the state space:

\[
\Delta \mu_i = \int_M d\mu(x) \chi_i(x) = \int_{M_i} d\mu(x) = \int_{M_i} dx \rho(x).
\]

(16.2)

The function \( \rho(x) = \rho(x,t) \) denotes the density of representative points in state space at time \( t \). This density can be (and in chaotic dynamics, often is) an arbitrarily ugly function, and it may display remarkable singularities; for instance, there may exist directions along which the measure is singular with respect to the Lebesgue measure (namely the uniform measure on the state space). We shall assume that the measure is normalized

\[
\sum_i \Delta \mu_i = 1,
\]

(16.3)

where the sum is over subregions \( i \) at the \( n \)th level of partitioning. The infinitesimal measure \( \rho(x) dx \) can be thought of as an infinitely refined partition limit of...
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Figure 16.2: The evolution rule \( f \) can be used to map a region \( M \) of the state space into the region \( f(M) \).

\[ \Delta \mu = |M| \rho(x_i) \, , \, x_i \in M, \text{ with normalization} \]
\[ \int_M dx \rho(x) = 1 \]  \hspace{1cm} (16.4)

Here \( |M| \) is the volume of region \( M \), and all \( |M| \rightarrow 0 \) as \( n \rightarrow \infty \).

So far, any arbitrary sequence of partitions will do. What are intelligent ways of partitioning state space? We already know the answer from chapter 11, but let us anyway develop some intuition about how the dynamics transports densities.

16.2 Perron-Frobenius operator

Given a density, the question arises as to what it might evolve into with time. Consider a swarm of representative points making up the measure contained in a region \( M \) at time \( t = 0 \). As the flow evolves, this region is carried into \( f(M) \), as in figure 16.2. No trajectory is created or destroyed, so the conservation of representative points requires that

\[ \int_{f(M)} dx \rho(x, t) = \int_M dx_0 \rho(x_0, 0) \] \hspace{1cm} (16.5)

Transform the integration variable in the expression on the left hand side to the initial points \( x_0 = f^{-1}(x) \),

\[ \int_M dx_0 \rho(f(x_0), t) |\det J f(x_0)| = \int_M dx_0 \rho(x_0, 0) \] \hspace{1cm} (16.6)

The density changes with time as the inverse of the Jacobian (4.46)

\[ \rho(x, t) = \frac{\rho(x_0, 0)}{|\det J f(x_0)|}, \quad x = f(x_0) \] \hspace{1cm} (16.7)

which makes sense: the density varies inversely with the infinitesimal volume occupied by the trajectories of the flow.

The relation (16.5) is linear in \( \rho \), so the manner in which a flow transports densities may be recast into the language of operators, by writing

\[ \rho(x, t) = \left( L_t \circ \rho \right)(x) = \int_M dx_0 \delta(x - f^t(x_0)) \rho(x_0, 0) \] \hspace{1cm} (16.8)

Let us check this formula. As long as the zero is not smack on the border of \( \partial M \) integrating Dirac delta functions is easy: \( \int_M dx_0 \delta(x) = 1 \) if \( 0 \in M \), zero otherwise.

The integral over a 1-dimensional Dirac delta function picks up the Jacobian of its argument evaluated at all of its zeros:

\[ \int dx \delta(h(x)) = \sum_{|x, h(x)| \neq 0} \frac{1}{|h'(x)|} \] \hspace{1cm} (16.9)

and in \( d \) dimensions the denominator is replaced by

\[ \int dx \delta(h(x)) = \sum_j \left( \int_{M_j} dx \delta(h(x)) \right) = \sum_{|x, h(x)| \neq 0} \frac{1}{|\det \frac{dh(x)}{dx}|} \] \hspace{1cm} (16.10)

Now you can check that (16.6) is just a rewrite of (16.5):

\[ \left( L^t \circ \rho \right)(x) = \sum_{x_0 \in \gamma^{-1}(x)} \frac{\rho(x_0)}{|\det J f(x_0)|} \] \hspace{1cm} (16.11)

For a deterministic, invertible flow \( x \) has only one preimage \( x_0 \); allowing for multiple preimages also takes account of noninvertible mappings such as the ‘stretch
16.3 Why not just leave it to a computer?

Another subtlety in the [dynamical systems] theory is that toponological and measure-theoretic concepts of genericity lead to different results.

— John Guckenheimer

(R. Artuso and P. Cvitanović)

To a student with a practical bent the above Example 16.1 suggests a strategy for constructing evolution operators for smooth maps, as limits of partitions of state space into regions \( \mathcal{M} \) with a piecewise-linear approximations \( f_i \) to the dynamics in each region, but that would be too naive: much of the physically interesting spectrum would be missed. As we shall see, the choice of function space for \( \rho \) is crucial, and the physically motivated choice is a space of smooth functions, rather than the space of piecewise constant functions.

All of the insight gained in this chapter and in what is to follow is nothing but an elegant way of thinking of the evolution operator, \( \mathcal{L} \), as a matrix (this point of view will be further elaborated in chapter 23). There are many textbook methods of approximating an operator \( \mathcal{L} \) by sequences of finite matrix approximations \( \mathcal{L} \), but in what follows the great achievement will be that we shall avoid constructing any matrix approximation to \( \mathcal{L} \) altogether. Why a new method? Why not just run it on a computer, as many do with such relish in diagonalizing quantum Hamiltonians?

The simplest possible way of introducing a state space discretization, figure 16.4, is to partition the state space \( \mathcal{M} \) with a non-overlapping collection of sets \( \mathcal{M}_i, i = 1, \ldots, N \), and to consider densities (16.2) piecewise constant on each \( \mathcal{M}_i \):

\[
\rho(x) = \sum_{i=1}^{N} \frac{\chi_i(x)}{|\mathcal{M}_i|} \rho_i(x),
\]

where \( \chi_i(x) \) is the characteristic function (16.1) of the set \( \mathcal{M}_i \). This piecewise constant density is a coarse grained presentation of a fine grained density \( \tilde{\rho}(x) \), with (16.2)

\[
\rho_i = \int_{\mathcal{M}_i} dx \tilde{\rho}(x).
\]

The Perron-Frobenius operator does not preserve the piecewise constant form, but we may reapply coarse graining to the evolved measure

\[
\rho'(x) = \int_{\mathcal{M}} dx (\mathcal{L} \circ \rho)(x) = \sum_{i=1}^{N} \frac{\rho_i}{|\mathcal{M}_i|} \int_{\mathcal{M}_i} dx \int_{\mathcal{M}_i} dy \delta(x - f(y)),
\]
16.4 Invariant measures

A stationary or invariant density is a density left unchanged by the flow

\[ \rho(x, t) = \rho(x, 0) = \rho(x) . \]

(16.15)

Conversely, if such a density exists, the transformation \( f'(x) \) is said to be measure-preserving. As we are given deterministic dynamics and our goal is the computation of asymptotic averages of observables, our task is to identify interesting invariant measures for a given \( f'(x) \). Invariant measures remain unaffected by dynamics, so they are fixed points (in the infinite-dimensional function space of \( \rho \) densities) of the Perron-Frobenius operator (16.10), with the unit eigenvalue: \( L \rho(x) = \int_M \delta(x - f'(y)) \rho(y) = \rho(x) \).

(16.16)

In general, depending on the choice of \( f'(x) \) and the function space for \( \rho(x) \), there may be no, one, or many solutions of the eigenfunction condition (16.16). For instance, a singular measure \( d\rho(x) = \delta(x - x_q) dx \) concentrated on an equilibrium point \( x_q = f'(x_q) \), or any linear combination of such measures, each concentrated on a different equilibrium point, is stationary. There are thus infinitely many stationary measures that can be constructed. Almost all of them are unnatural in the sense that the slightest perturbation will destroy them.

From a physical point of view, there is no way to prepare initial densities which are singular, so we shall focus on measures which are limits of transformations experienced by an initial smooth distribution \( \rho(x) \) under the action of \( f \):

\[ \rho_\alpha(x) = \lim_{j \to \infty} \int_M dy \, \delta(x - f'(y)) \rho(y, 0), \quad \int_M dy \, \rho(y, 0) = 1 . \]

(16.17)

Intuitively, the “natural” measure should be the measure that is the least sensitive to the (in practice unavoidable) external noise, no matter how weak.
16.4.1 Natural measure

Huang: Chen-Ning, do you think ergodic theory gives us useful insight into the foundation of statistical mechanics?
Yang: I don’t think so.

—Kerson Huang, C.N. Yang interview

In computer experiments, as the Hénon example of figure 16.5, the long time evolution of many “typical” initial conditions leads to the same asymptotic distribution. Hence the natural (also called equilibrium measure, SRB measure, Sinai-Bowen-Ruelle measure, physical measure, invariant density, natural density, or even “natural invariant”) is defined as the limit

\[
\rho_n(y) = \begin{cases} 
\lim_{t \to \infty} \frac{1}{t} \int_0^t \delta(y - f^t(x_0)) \text{ flows} \\
\lim_{n \to \infty} \frac{1}{2^n} \sum_{k=0}^{2^n-1} \delta(y - f^k(x_0)) \text{ maps},
\end{cases}
\]

(16.18)

where \(x_0\) is a generic initial point. Generated by the action of \(f\), the natural measure satisfies the stationarity condition (16.16) and is thus invariant by construction.

Staring at an average over infinitely many Dirac deltas is not a prospect we cherish. From a computational point of view, the natural measure is the visitation frequency defined by coarse-graining, integrating (16.18) over the \(\mathcal{M}\) region

\[
\Delta \rho_n = \lim_{t \to \infty} \frac{t}{t} 
\]

(16.19)

where \(t_i\) is the accumulated time that a trajectory of total duration \(t\) spends in the \(\mathcal{M}\) region, with the initial point \(x_0\) picked from some smooth density \(\rho(x)\).

Let \(a = a(x)\) be any observable. In the mathematical literature \(a(x)\) is a function belonging to some function space, for instance the space of integrable functions \(L^1\), that associates to each point in state space a number or a set of numbers. In physical applications the observable \(a(x)\) is necessarily a smooth function. The observable reports on some property of the dynamical system. Several examples will be given in sect. 17.1.

The space average of the observable \(a\) with respect to a measure \(\rho\) is given by the \(d\)-dimensional integral over the state space \(\mathcal{M}\):

\[
\langle a \rangle_\rho = \frac{1}{\rho(\mathcal{M})} \int_M dx \rho(x) a(x)
\]

(16.20)

For now we assume that the state space \(\mathcal{M}\) has a finite dimension and a finite volume. By definition, \(\langle a \rangle_\rho\) is a function(al) of \(\rho\). For \(\rho = \rho_0\) natural measure we shall drop the subscript in the definition of the space average: \(\langle a \rangle_\rho = \langle a \rangle\).

Inserting the right-hand-side of (16.18) into (16.20), we see that the natural measure corresponds to a time average of the observable \(a\) along a trajectory of the initial point \(x_0\),

\[
\langle a \rangle = \lim_{t \to \infty} \frac{1}{t} \int_0^t dt a(f^t(x_0)) .
\]

(16.21)

Analysis of the above asymptotic time limit is the central problem of ergodic theory. The Birkhoff ergodic theorem asserts that if an invariant measure \(\rho\) exists, the limit \(\langle a \rangle\) for the time average (16.21) exists for (almost) all initial \(x_0\). Still, Birkhoff theorem says nothing about the dependence on \(x_0\) of time averages \(\langle a \rangle\), or, equivalently, that the construction of natural measures (16.18) leads to a “single” density, independent of \(x_0\). This leads to one of the possible definitions of an ergodic evolution: \(f\) is ergodic if for any integrable observable \(a\) in (16.21) the limit function is constant. If a flow enjoys such a property the time averages coincide (apart from a set of measure 0) with space averages

\[
\lim_{t \to \infty} \frac{1}{t} \int_0^t dt a(f^t(x_0)) = \langle a \rangle .
\]

(16.22)

For future reference, we note a further property that is stronger than ergodicity: if the space average of a product of any two variables decorrelates with time,

\[
\lim_{t \to \infty} \langle a(x) b(f^t(x)) \rangle = \langle a \rangle \langle b \rangle ,
\]

(16.23)

the dynamical system is said to be mixing. The terminology may be understood better once we consider as the pair of observables in (16.23) characteristic functions of two sets \(A\) and \(B\): then (16.23) may be written as

\[
\lim_{t \to \infty} \mu(A \cap f^t(B)) \mu(A) = \mu(B)
\]

so that the set \(B\) spreads “uniformly” over the whole state space as \(t\) increases. Mixing is a fundamental notion in characterizing statistical behavior for dynamical systems: suppose we start with an arbitrary smooth nonequilibrium distribution \(\rho(x)\nu(x)\): the after time \(t\) the average of an observable \(a\) is given by

\[
\int_M dx \rho(x) \nu(x) f^t(x) a(x)
\]

and this tends to the equilibrium average \(\langle a \rangle\) if \(f\) is mixing.

Example 16.2 The Hénon attractor natural measure: A numerical calculation of the natural measure (16.19) for the Hénon attractor (3.19) is given by the histogram in figure 16.5. The state space is partitioned into many equal-size areas \(\mathcal{M}\), and the coarse grained measure (16.19) is computed by a long-time iteration of the Hénon map, and represented by the height of the column over area \(\mathcal{M}\). We what see is a typical invariant measure - a complicated, singular function concentrated on a fractal set.
If an invariant measure is quite singular (for instance a Dirac δ concentrated on a fixed point or a cycle), its existence is most likely of no physical import; no smooth initial density will converge to this measure if its neighborhood is repelling. In practice the average (16.18) is problematic and often hard to control, as generic dynamical systems are neither uniformly hyperbolic nor structurally stable: it is not known whether even the simplest model of a strange attractor, the Hénon attractor of figure 16.5, is “strange,” or merely a transient to a very long stable cycle.

16.4.2 Determinism vs. stochasticity

While dynamics can lead to very singular ρ’s, in any physical setting we cannot do better than to measure ρ averaged over some region $M$; the coarse-graining is not an approximation but a physical necessity. One is free to think of a measure as a probability density, as long as one keeps in mind the distinction between deterministic and stochastic flows. In deterministic evolution the evolution kernels are not probabilistic; the density of trajectories is transported deterministically. What this distinction means will become apparent later: for deterministic flows our trace and determinant formulas will be exact, while for quantum and stochastic flows they will only be the leading saddle point (stationary phase, steepest descent) approximations.

Clearly, while deceptively easy to define, measures spell trouble. The good news is that if you hang on, you will never need to compute them, at least not in this book. How so? The evolution operators to which we next turn, and the trace and determinant formulas to which they will lead us, will assign the correct weights to desired averages without recourse to any explicit computation of the coarse-grained measure $\Delta \rho$.

16.5 Density evolution for infinitesimal times

Consider the evolution of a smooth density $\rho(x) = \rho(x,0)$ under an infinitesimal step $\delta \tau$, by expanding the action of $L^{\delta \tau}$ to linear order in $\delta \tau$:

$$ L^{\delta \tau} \rho(y) = \int_M dx \delta (y - \delta \tau v(x)) \rho(x) $$

Exercise 4.1

Here we have used the infinitesimal form of the flow (2.6), the Dirac delta Jacobian (16.9), and the $\ln \det A$ expansion (16.19). In particular, for the density $\rho$ of a drift $v$ a solution $\rho(x,0)$ to the left hand side and dividing by $\delta \tau$, we discover that the rate of the deformation of $\rho$ under the infinitesimal action of the Perron-Frobenius operator is nothing but the continuity equation for the density:

$$ \partial_t \rho + \nabla \cdot (\rho v) = 0. $$

(16.25)

The family of Perron-Frobenius operators $\{L^t\}_{t \in \mathbb{R}}$ forms a semigroup parameterized by time

(a) $L^0 = I$

(b) $L^t L^{t'} = L^{t+t'} \quad t, t' \geq 0$ (semigroup property).

From (16.24), time evolution by an infinitesimal step $\delta \tau$ forward in time is generated by

$$ A \rho(x) = + \lim_{\delta \tau \to 0} \frac{1}{\delta \tau} (L^{\delta \tau} - I) \rho(x) = -\partial_t (v(x) \rho(x)). $$

(16.26)

We shall refer to

$$ A = -\partial \cdot v + \sum_i v_i(x) \partial_i $$

(16.27)

as the time evolution generator. If the flow is finite-dimensional and invertible, $A$ is a generator of a full-fledged group. The left hand side of (16.26) is the definition of time derivative, so the evolution equation for $\rho(x)$ is

$$ \left( \frac{\partial}{\partial t} - A \right) \rho(x) = 0. $$

(16.28)

The finite time Perron-Frobenius operator (16.10) can be formally expressed by exponentiating the time evolution generator $A$ as

$$ L^t = e^{tA}. $$

(16.29)
The generator $\mathcal{A}$ is reminiscent of the generator of translations. Indeed, for a constant velocity field dynamical evolution is nothing but a translation by \( (t \times v) \):

\[
e^{t \mathcal{A}}a(x) = a(x - tv).
\]

(16.30)

16.5.1 Resolvent of $\mathcal{L}$

Here we limit ourselves to a brief remark about the notion of the “spectrum” of a linear operator.

The Perron-Frobenius operator $\mathcal{L}$ acts multiplicatively in time, so it is reasonable to suppose that there exist constants $M > 0$, $\beta \geq 0$ such that $\| \mathcal{L} \| \leq M e^{\beta t}$ for all $t \geq 0$. What does that mean? The operator norm is defined in the same spirit in which one defines matrix norms. We are assuming that no value of $\mathcal{L}' \rho(x)$ grows faster than exponentially for any choice of function $\rho(x)$, so that the fastest possible growth can be bounded by $e^{\beta t}$, a reasonable expectation in the light of the simplest example studied so far, the exact escape rate (17.20). If that is so, multiplying $\mathcal{L}$ by $e^{-\beta t}$ we construct a new operator $e^{-\beta t} \mathcal{L}' = e^{-\beta t} \mathcal{L}$ which decays exponentially for large $t$, $\| e^{\beta t} \mathcal{L} \| \leq M$. We say that $e^{-\beta t} \mathcal{L}'$ is an element of a bounded semigroup with generator $\mathcal{A} - \beta I$. Given this bound, it follows by the Laplace transform

\[
\int_0^\infty dt\ e^{-st} \mathcal{L}' = \frac{1}{s - \mathcal{A}}, \quad Re s > \beta,
\]

(16.31)

that the resolvent operator $(s - \mathcal{A})^{-1}$ is bounded ("resolvent" = able to cause separation into constituents)

\[
\frac{1}{s \mathcal{A}} \leq \int_0^\infty dt\ e^{-st} Me^{\beta t} = \frac{M}{s - \beta}.
\]

If one is interested in the spectrum of $\mathcal{L}$, as we will be, the resolvent operator is a natural object to study; it has no time dependence, and it is bounded. The main lesson of this brief aside is that for continuous time flows, the Laplace transform is the tool that brings down the generator in (16.29) into the resolvent form (16.31) and enables us to study its spectrum.

16.6 Liouville operator

A case of special interest is the Hamiltonian or symplectic flow defined by Hamilton’s equations of motion (7.1). A reader versed in quantum mechanics will have observed by now that with replacement $\mathcal{A} \rightarrow -\frac{i}{\hbar} \hat{H}$, where $\hat{H}$ is the quantum Hamiltonian operator, (16.28) looks rather like the time dependent Schrödinger equation, so this is probably the right moment to figure out what all this means in the case of Hamiltonian flows.

The Hamilton’s evolution equations (7.1) for any time-independent quantity $Q = Q(q, p)$ are given by

\[
\frac{dQ}{dt} = \frac{\partial Q}{\partial q} \frac{dq}{dt} + \frac{\partial Q}{\partial p} \frac{dp}{dt} = \frac{\partial Q}{\partial q} \frac{\partial H}{\partial p} - \frac{\partial Q}{\partial p} \frac{\partial H}{\partial q}.
\]

(16.32)

As equations with this structure arise frequently for symplectic flows, it is convenient to introduce a notation for them, the Poisson bracket

\[
\{A, B\} = \frac{\partial A}{\partial p} \frac{\partial B}{\partial q} - \frac{\partial A}{\partial q} \frac{\partial B}{\partial p}.
\]

(16.33)

In terms of Poisson brackets the time evolution equation (16.32) takes the compact form

\[
\frac{dQ}{dt} = \{H, Q\}.
\]

(16.34)

The full state space flow velocity is $\dot{x} = v = (\dot{q}, \dot{p})$, where the dot signifies time derivative.

The discussion of sect. 16.5 applies to any deterministic flow. If the density itself is a material invariant, combining

\[
\partial_v + v \cdot \partial_I = 0,
\]

and (16.25) we conclude that $\partial_v v_v = 0$ and $det J(\mathbf{q}_0) = 1$. An example of such incompressible flow is the Hamiltonian flow of sect. 7.2. For incompressible flows the continuity equation (16.25) becomes a statement of conservation of the state space volume (see sect. 7.2), or the Liouville theorem

\[
\partial_v \rho + v \cdot \partial \rho = 0.
\]

(16.35)

Hamilton’s equations (7.1) imply that the flow is incompressible, $\partial_v v_v = 0$, so for Hamiltonian flows the equation for $\rho$ reduces to the continuity equation for the phase space density:

\[
\partial_v \rho + \partial(\rho v_v) = 0, \quad i = 1, 2, \ldots, D.
\]

(16.36)
Consider the evolution of the phase space density $\rho$ of an ensemble of noninteracting particles; the particles are conserved, so

$$\frac{d}{dt} \rho(q, p, t) = \left( \frac{\partial}{\partial t} + \frac{\partial}{\partial q_i} \dot{q}_i + \frac{\partial}{\partial p_i} \dot{p}_i \right) \rho(q, p, t) = 0.$$  

Inserting Hamilton’s equations (7.1) we obtain the Liouville equation, a special case of (16.28):

$$\frac{d}{dt} \rho(q, p, t) = - \mathcal{A} \rho(q, p, t) = \{H, \rho(q, p, t)\},$$  

(16.37)

where $\{,\}$ is the Poisson bracket (16.33). The generator of the flow (16.27) is in this case a generator of infinitesimal symplectic transformations,

$$\mathcal{A} = \frac{\partial}{\partial q_i} \frac{\partial}{\partial p_i} - \frac{\partial}{\partial q_i} \frac{\partial}{\partial p_i} + \frac{\partial H}{\partial q_i} \frac{\partial}{\partial q_i} - \frac{\partial H}{\partial p_i} \frac{\partial}{\partial p_i}.$$  

(16.38)

For example, for separable Hamiltonians of form $H = p^2/(2m) + V(q)$, the equations of motion are

$$\dot{q}_i = \frac{p_i}{m}, \quad \dot{p}_i = -\frac{\partial V(q)}{\partial q_i},$$  

(16.39)

and the action of the generator

$$\mathcal{A} = \frac{p_i}{m} \frac{\partial}{\partial q_i} + \frac{\partial V(q)}{\partial p_i} \frac{\partial}{\partial p_i}.$$  

(16.40)

can be interpreted as a translation (16.30) in configuration space, followed by acceleration by force $\partial V(q)$ in the momentum space.

The time evolution generator (16.27) for the case of symplectic flows is called the Liouville operator. You might have encountered it in statistical mechanics, while discussing what ergodicity means for $10^{23}$ hard balls. Here its action will be very tangible; we shall apply the Liouville operator to systems as small as 1 or 2 hard balls and to our surprise learn that this suffices to already get a bit of a grip on foundations of the nonequilibrium statistical mechanics.

**Résumé**

In physically realistic settings the initial state of a system can be specified only to a finite precision. If the dynamics is chaotic, it is not possible to calculate accurately the long time trajectory of a given initial point. Depending on the desired precision, and given a deterministic law of evolution, the state of the system can then be tracked for a finite time.

The study of long-time dynamics thus requires trading in the evolution of a single state space point for the evolution of a measure, or the density of representative points in state space, acted upon by an evolution operator. Essentially this means trading in nonlinear dynamical equations on a finite dimensional space $x = (x_1, x_2, \cdots, x_d)$ for a linear equation on an infinite dimensional vector space of density functions $\rho(x)$. For finite times and for maps such densities are evolved by the Perron-Frobenius operator,

$$\rho(x, t) = \mathcal{L}^t \rho,$$

and in a differential formulation they satisfy the continuity equation:

$$\partial_t \rho + \partial \cdot (\rho \mathbf{v}) = 0.$$  

The most physical of stationary measures is the natural measure, a measure robust under perturbations by weak noise.

Reformulated this way, classical dynamics takes on a distinctly quantum-mechanical flavor. If the Lyapunov time (1.1), the time after which the notion of an individual deterministic trajectory loses meaning, is much shorter than the observation time, the “sharp” observables are those dual to time, the eigenvalues of evolution operators. This is very much the same situation as in quantum mechanics; as atomic time scales are so short, what is measured is the energy, the quantum-mechanical observable dual to the time. For long times the dynamics is described in terms of stationary measures, i.e., fixed points of the appropriate evolution operators. Both in classical and quantum mechanics one has a choice of implementing dynamical evolution on densities (“Schrödinger picture,” sect. 16.5) or on observables (“Heisenberg picture,” sect. 17.2 and chapter 18).

In what follows we shall find the second formulation more convenient, but the alternative is worth keeping in mind when posing and solving invariant density problems. However, as classical evolution operators are not unitary, their eigenstates can be quite singular and difficult to work with. In what follows we shall learn how to avoid dealing with these eigenstates altogether. As a matter of fact, what follows will be a labor of radical deconstruction; after having argued so strenuously here that only smooth measures are “natural,” we shall merrily proceed to erect the whole edifice of our theory on periodic orbits, i.e., objects that are $\delta$-functions in state space. The trick is that each comes with an interval, its neighborhood – periodic orbits only serve to pin these intervals, just as the millimeter marks on a measuring rod partition continuum into intervals.
CHAPTER 16. TRANSPORTING DENSITIES

Commentary

Remark 16.1 Ergodic theory: An overview of ergodic theory is outside the scope of this book: the interested reader may find it useful to consult refs. [16.1, 16.3, 16.4, 16.5]. The existence of time average (16.21) is the basic result of ergodic theory, known as the Birkhoff theorem, see for example refs. [16.1, 16.25], or the statement of theorem 7.3.1 in ref. [16.12]. The natural measure (16.19) of sect. 16.4.1 is often referred to as the SRB or Sinai-Ruelle-Bowen measure [1.29, 1.28, 1.32].

There is much literature on explicit form of natural measure for special classes of 1-dimensional maps [1.19, 16.14, 16.15] - J. M. Aguirregabiria [16.16], for example, discusses several families of maps with known smooth measure, and behavior of measure under smooth conjugacies. As no such explicit formulas exist for higher dimensions and general dynamical systems, we do not discuss such measures here.

Remark 16.2 Time evolution as a Lie group: Time evolution of sect. 16.5 is an example of a 1-parameter Lie group. Consult, for example, chapter 2 of ref. [16.13] for a clear and pedagogical introduction to Lie groups of transformations. For a discussion of the bounded semigroups of page 321 see, for example, Marsden and Hughes [16.6].

Remark 16.3 Discretization of the Perron-Frobenius operator operator: It is an old idea of Ulam [16.18] that such an approximation for the Perron-Frobenius operator is a meaningful one. The piecewise-linear approximation of the Perron-Frobenius operator (16.14) has been shown to reproduce the spectrum for expanding maps, once finer and finer Markov partitions are used [16.19, 16.23, 16.20]. The subtle point of choosing a state space partitioning for a “generic case” is discussed in ref. [16.21, 23.22].

Remark 16.4 The sign convention of the Poisson bracket: The Poisson bracket is antisymmetric in its arguments and there is a freedom to define it with either sign convention. When such freedom exists, it is certain that both conventions are in use and this is no exception. In some texts [1.8, 16.7] you will see the right hand side of (16.33) defined as [B, A] so that (16.34) is \( \frac{\partial}{\partial t} = \{Q, H\} \). Other equally reputable texts [16.24] employ the convention used here. Landau and Lifshitz [16.8] denote a Poisson bracket by \([A, B]\), notation that we reserve here for the quantum-mechanical commutator. As long as one is consistent, there should be no problem.

Remark 16.5 “Anon it lives?” “Anon it lives” refers to a statue of King Leon'tes’s wife, Hermione, who died in a fit of grief after he unjustly accused her of infidelity. Twenty years later, the servant Paulina shows Leontes this statue of Hermione. When he repents, the statue comes to life. Or perhaps Hermione actually lived and Paulina has kept her hidden all these years. The text of the play seems deliberately ambiguous. It is probably a parable for the resurrection of Christ. (John F. Gibson)

Exercises

16.1. Integrating over Dirac delta functions. Let us verify a few of the properties of the delta function and check (16.9), as well as the formulas (16.7) and (16.8) to be used later.
(a) If \( f: \mathbb{R} \rightarrow \mathbb{R}^d \), show that
\[
\int_{\mathbb{R}^d} \delta (f(x)) = \sum_{\mathbb{N}^{d}} \frac{1}{|\det \partial_{f}(x)|}
\]
(b) The delta function can be approximated by a sequence of Gaussians
\[
\int_{\mathbb{R}} \delta (\chi (x)) \approx \lim_{\sigma \rightarrow 0} \int_{\mathbb{R}} e^{-\frac{x^2}{2\sigma^2}} \delta (x)
\]
Use this approximation to see whether the formal expression
\[
\int_{\mathbb{R}} \delta (\chi^2)
\]
makes sense.

16.2. Derivatives of Dirac delta functions. Consider \( \partial^2 \delta (x) = \frac{\partial}{\partial x} \delta (x) \).

Using integration by parts, determine the value of
\[
\int_{\mathbb{R}} \partial^2 \delta (x) \text{ } , \quad \text{where } y = f(x) - x \quad (16.41)
\]
\[
\int_{\mathbb{R}} \partial x \partial ^2 \delta (y) = \sum_{\{i,j\}=0} \frac{1}{|v|} \left( \frac{\partial^2}{\partial y^i \partial y^j} \right)_{(y)}
\]
\[
\int_{\mathbb{R}} \partial y \partial^2 \delta (y) = \sum_{\{i,j\}=0} \frac{1}{|v|} \left( \frac{\partial^2}{\partial y^i \partial y^j} \right)_{(y)} + \frac{1}{|v|} \delta (y)
\]
(16.43)

These formulas are useful for computing effects of weak noise on deterministic dynamics [16.49].

16.3. \( L \) generates a semigroup. Check that the Perron-Frobenius operator has the semigroup property.
\[
\int_{\mathbb{R}} dQ (y,z) L (x,y) = L (x,z)
\]
As the flows in which we tend to be interested are invertible, the \( L \)'s that we will use often do form a group, with \( t_1, t_2 \in \mathbb{R} \).

16.4. Escape rate of the tent map.

16.5. Invariant measure. We will compute the invariant measure for two different piecewise linear maps.

16.6. Escape rate for a flow conserving map. Adjust \( \mu_0 \) in (17.17) so that the gap between the intervals \( M_0 \) and \( M_1 \) vanishes. Show that the escape rate equals zero in this situation.

16.7. Eigenvalues of the Perron-Frobenius operator for the skew full tent map. Show that for the skew full tent map
a bit of unpleasantness to which we shall return in chapter 24.

16.9. Invariant measure for the Gauss map. Consider the Gauss map:

\[ f(x) = \begin{cases} \frac{1}{2} - \left\lfloor \frac{1}{2} \right\rfloor & x \neq 0 \\ 0 & x = 0 \end{cases} \]  

(16.46)

where \( \lfloor \cdot \rfloor \) denotes the integer part.

(a) Verify that the density \( \rho(x) = \frac{1}{\log 2} \frac{1}{1 + x} \) is an invariant measure for the map. \( \rho(x) \) is the natural measure?

16.10. \( \Lambda \) as a generator of translations. Verify that for a constant velocity field the evolution generator \( \Lambda \) in (16.30) is the generator of translations,

\[ e^{t\Lambda} \phi(x) = \phi(x + tv) \]

16.11. Incompressible flows. Show that (16.9) implies that \( \rho_0(x) = 1 \) is an eigenfunction of a volume-preserving flow with eigenvalue \( \rho_0 = 0 \). In particular, this implies that the natural measure of hyperbolic and mixing Hamiltonian flows is uniform. Compare this results with the numerical experiment of exercise 16.8.

References


